

Frist Person Sketch-based Terrain Editing

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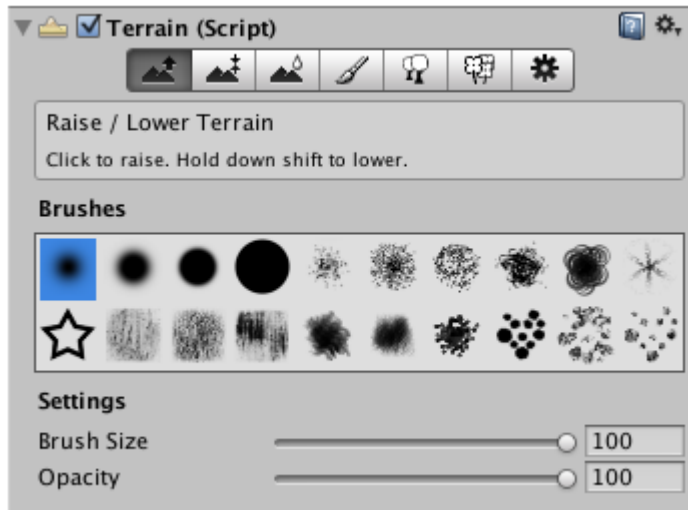
Topics

- Analyzing complex terrain (and sketches)
- Feature detection and matching
- *A minimization* problem
- Terrain deformation

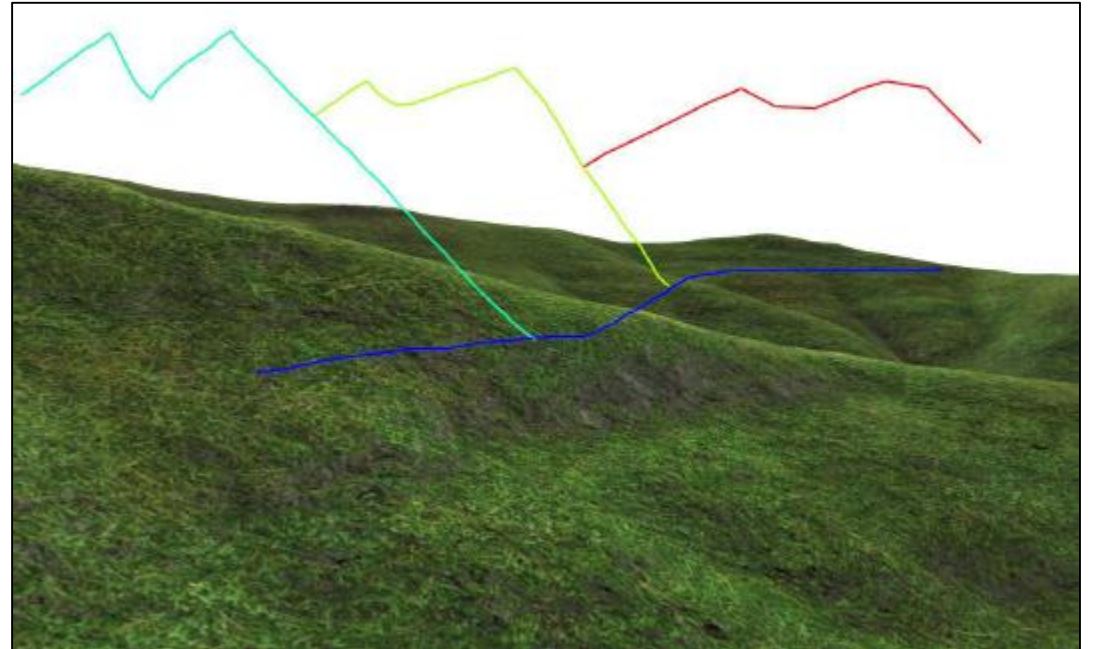
The Goal



https://www.youtube.com/watch?time_continue=2&v=HjZBhUsKa3s&ab_channel=UE4Docs

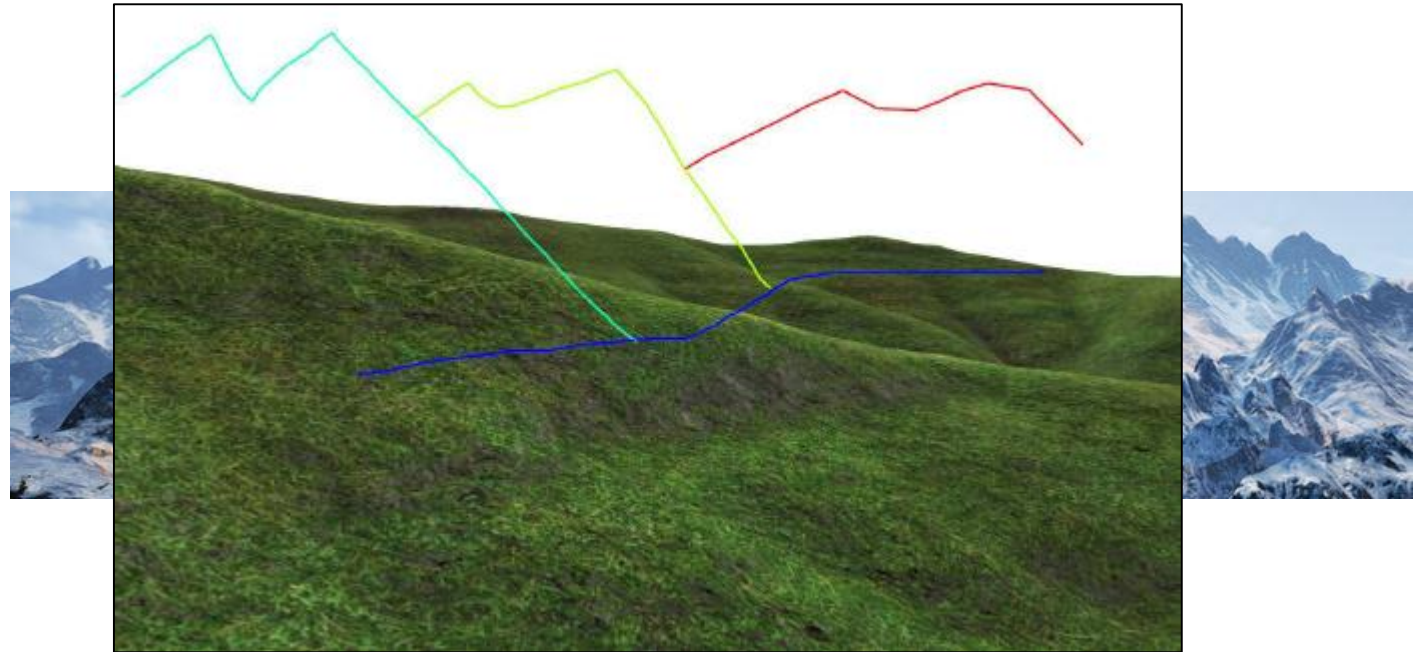


<https://docs.unity3d.com/Manual/terrain-UsingTerrains.html>



What are we working with?

- Terrain
 - Mesh
 - Height map
 - Texture(s)
 - 3D (X, Y, Z)
 - Ridges (static)
 - Silhouettes (non-static)
- Sketch
 - A set of 2D strokes



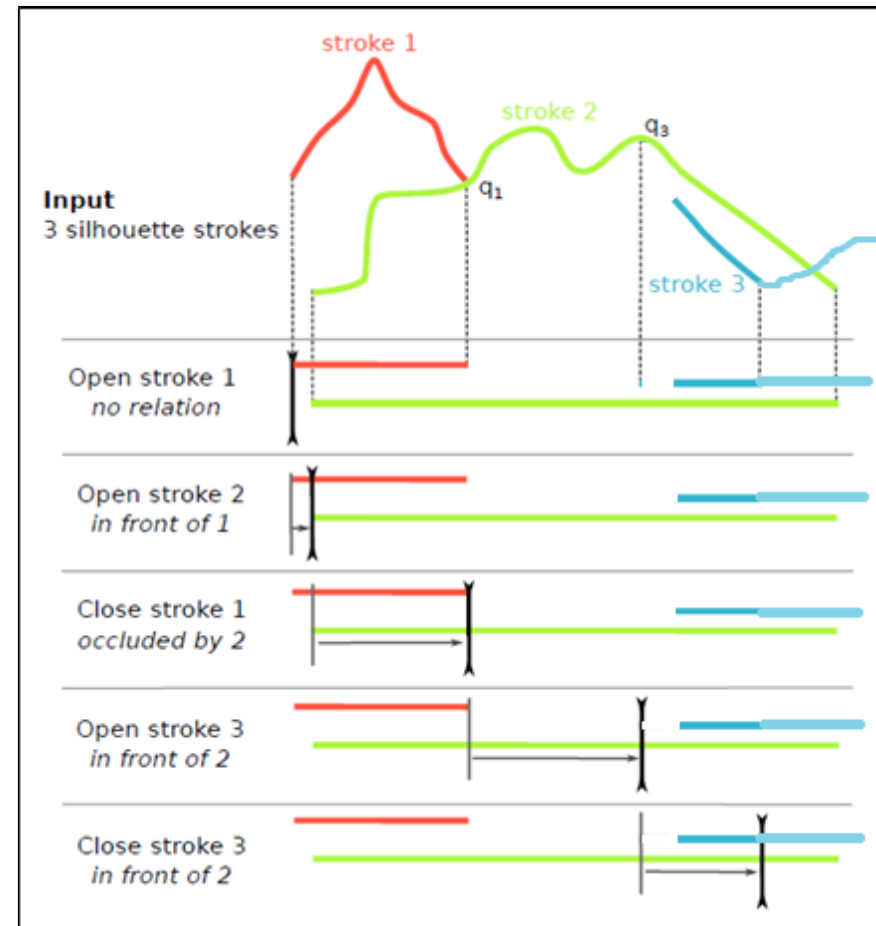
<https://forum.unity.com/threads/terrain-nature-918505/>
<https://en.wikipedia.org/wiki/Heightmap>
<https://www.gamedev.net/forums/topic/166909-terrain-look-awful-in-one-project/>

Requirements

- 1) Every sketched stroke should be a terrain silhouette, given the current perspective view from the first-person camera viewpoint
- 2) Each of these terrain silhouettes should be visible, i.e. not hidden by any other part of the terrain
- 3) The deformed terrain should not have artifacts nor contain unrealistic deformations from any other viewpoint

Step 1 – order sketched strokes by depth

- T-junctions
 - $\|q_s - \text{closest}(r)\| < \text{threshold}$
 - q_s occluded by q_r if
 - $\angle(t_s, t_r) < 180^\circ$
- No T-junctions
 - Stroke s in front of stroke r if
 - r completely contains s
 - $\text{min_height}(q_s) > \text{min_height}(q_r)$



Step 2 – feature detection

Given a polygon mesh:

- Silhouettes
 - All visible edges shared by a front face and a back face in the current perspective view -> link neighboring silhouette curves
- Ridges (PPA algorithm Chang[3])
 - Connect likely (magic) ridge points
 - Polygon-breaking on cyclic components by lowest height value until acyclic



Step 3 – stroke-feature matching

- For a stroke s_i
 - Project all terrain features $f_j : j \in 1 \dots n$ onto the sketching plane (2D)
 $f_p : p \in 1 \dots n$
 - Keep feature on condition: $range(f_{j_x}) \geq range(s_{i_x})$
 - Deform each remaining feature:
 - $q.z = q.z + k \|q_p - q_p^s\| * \frac{\|q - eye\|}{\|q_p - eye\|}, q \in f_j, q_p \in f_{j_p}$
 - $q_p^s = intersection(q_p, s)$
- $k = -1$ if f_p is below s and $k = 1$ otherwise

Step 4 – feature cost

- $E = E_{dissimilarity} + E_{deformation} + E_{sampling} + E_{extension}$

- $E_{dissimilarity}(f) = \frac{w1}{curvelength(f_p)} * \int_{f_p} h_{f_p} dt$

- $E_{deformation}(f) = \frac{w2}{curvelength(f_p)} * \int_f h_f dt$

- $E_{sampling}(f) = w3 * \frac{longestedglength(f)}{\max_{g \in prioritylist(s)} longestedglength(g)}$

- $E_{extension}(f) = w4 * \frac{extendedcurvelength(f)}{curvelength(f)}$

- w_i are weights (= 1.0 in the paper)

- $H_{f_p} = |f_p \cdot z - s \cdot z|$

- $H_f = |f \cdot z - f_p \cdot z|$

Step 5 - minimization

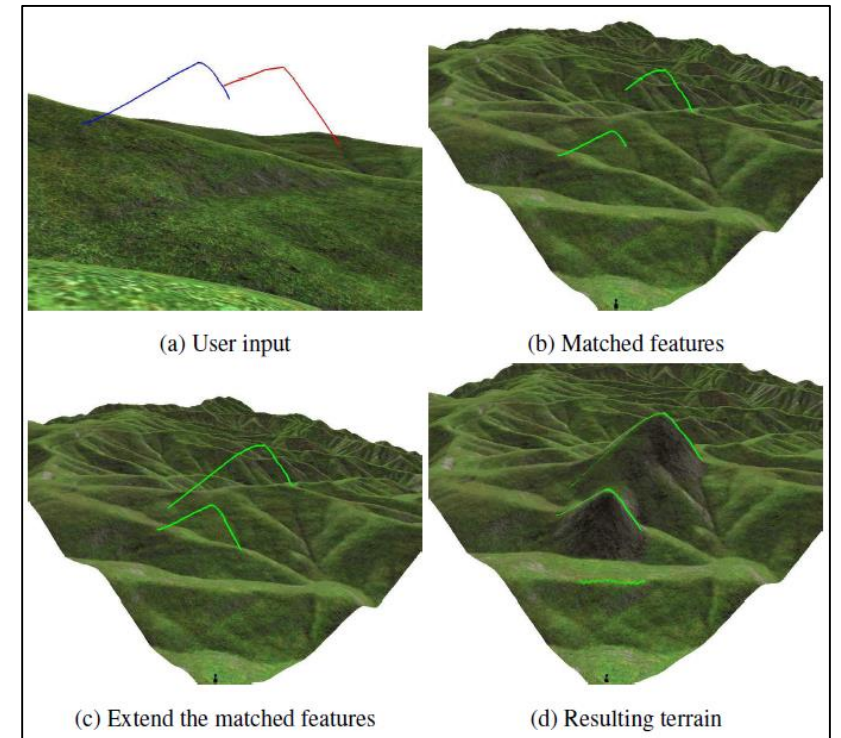
- Goal: select a feature curve for each stroke s

```
1 for s in strokes:
2     feature = init_max_cost_feature()
3     for f_i in s.features:
4         cont = True
5         for f_j in s.features(j > i):
6             if f_i >= f_j: #f_j occludes f_i
7                 cont = False
8                 break
9         if cont and E(f_i) < feature.energy:
10            feature = f_i
```

- NP-hard problem
 - $O(sf^2)$, $s = \text{len}(\text{strokes})$, $f = \text{len}(s.\text{features})$
- Feature elimination

Step 6 – project strokes

- Strokes: screen space \rightarrow world space
 - $\forall q_s = (x_s, z_s) \in s$
 - *find* $q_p = (x_p, z_p) = (x_s, z_s) = q_s$,
where q_p is the projection of a feature point q_f
 - Undetermined points follow tangent
- Stroke endpoints can be un-natural
 - Extend features along endpoint tangents until an intersection occurs



Step 7 – terrain deformation

- We have worked on features, not deformed the terrain

```
1 for point on stroke:  
2     delta = point.height - height_map(p.x, p.y)  
3     displacement_map(p.x, p.y) = delta  
4  
5 new_height_map = height_map + displacement_map
```

- Solve user-defined silhouettes being hidden by lowering terrain

- Rerun

```
1 for point on stroke:  
2     delta = point.height - height_map(p.x, p.y)  
3     displacement_map(p.x, p.y) = delta  
4  
5 new_height_map = height_map + displacement_map
```

Voilà

